Introduction to Parallel Programming

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Outline



- Resources
- 2 Parallel Architectures Today
- 3 A short history of parallel programming and why we need it
- Message-passing execution models
 - Standard Features & Execution Model
 - MPI Basics: Features, Compilation, Execution
 - Non-Blocking Communications
 - Collective operations
- 5 Shared-memory execution models
 - Introduction to OpenMP
 - OpenMP Basics
 - Learning More About Shared-Memory Models
 - **References**

Resources

Resources I



Standards and specifications

- ▶ OpenMP: [Dagum and Menon 1998; Duran et al. 2011; Ayguade et al. 2009]
 - Useful books: Using OpenMP [Chapman, Jost, and Van Der Pas 2008]
 - http://www.openmp.org
- ▶ MPI: [Graham 2009; Dongarra et al. 1995; Forum 1994]
 - Useful books:
 - Using MPI [Gropp, Lusk, and Skjellum 1999; Gropp, Lusk, and Skjellum 2014] (latest: 3rd edition),
 - Using MPI-2 [Gropp, Lusk, and Thakur 1999]
 - Using Advanced MPI [Gropp, Hoefler, et al. 2014]
 - http://mpi-forum.org
 - http://www.mcs.anl.gov/mpi
- PGAS: http://www.pgas.org
- Accelerator programming:
 - Cuda: https://developer.nvidia.com/cuda-zone
 - OpenCL: https://www.khronos.org, in particular https://www.khronos.org/opencl/
 - OpenACC: https://www.openacc.org

Resources II



Available implementations

- ▶ OpenMP: Clang, GCC since v4.2 (proprietary implementations include Intel's ICC, IBM XL C; etc.)
 - Note: GCC's OpenMP runtime is more of a reference implementation than anything.
 - Intel's runtime implementation of OpenMP is free software, and used by Clang. You
 can also download it and link it to GCC.
- MPI: Mpich-2, Open-MPI
 - Most supercomputer vendors provide their own implementation, often derived from either Mpich or Open-MPI
 - Personal preference: Open-MPI (more modular; more recent-benefits from design issues found in Mpich)
- ▶ OpenACC: GCC since v5 (the proprietary PGI compiler also implements it)
- ▶ OpenCL: libclc on LLVM (Clang/LLVM)

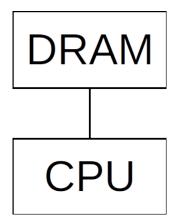
Parallel Architectures Today

General Purpose Architectures I

An Overview



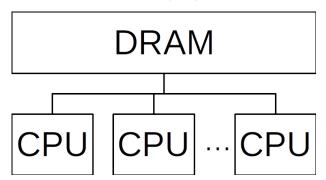
Figure: Single CPU and a single DRAM bank.



General Purpose Architectures II An Overview



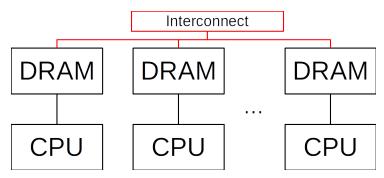
Figure: Symmetric Multi-Processor (SMP) system; single DRAM bank.



General Purpose Architectures III An Overview



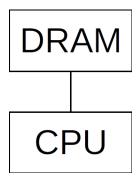
Figure: Symmetric Multi-Processor (SMP) system with Non-Uniform Memory Access (NUMA); multiple DRAM banks.



General Purpose Architectures IV An Overview



Figure: Single CPU and a single DRAM bank.

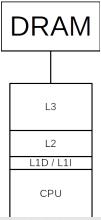


General Purpose Architectures V



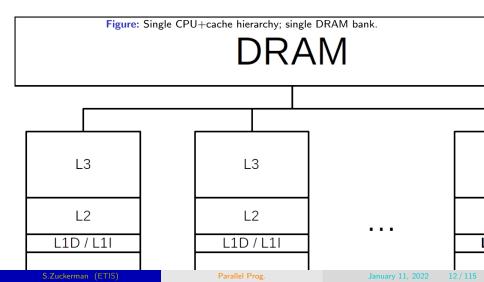
An Overview

Figure: Single CPU: CPU, L1 data cache (L1D), L1 Instruction cache (L1I), L2 unified cache (L2), L3 Unified cache (L3); single DRAM bank.



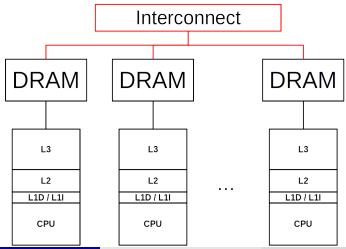
General Purpose Architectures VI An Overview





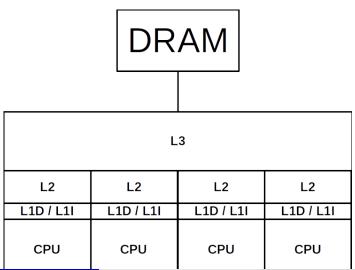
General Purpose Architectures VII An Overview





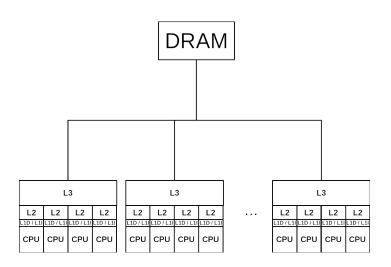
General Purpose Architectures VIII An Overview





General Purpose Architectures IX An Overview

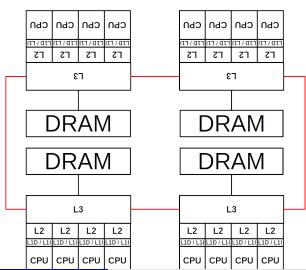




General Purpose Architectures X

An Overview





A short history of parallel programming and why we need it

In the beginning... I

Why parallel computing?

- Parallel programming appears very early in the life of computing.
- ► For every generation of high-end processor, some computations hog all of the available resources.
- Solution: duplicate computing resources.

In the beginning... II

Two (non-exclusive) approaches

- ▶ Design a parallel processor/computer architecture, i.e., duplicate functional units, provide vector units, . . . :
 - Cray I vector supercomputer
 - Connection Machine
- Design a computer made of multiple computing nodes (also called compute nodes):
 - Custom clusters: SGI Altix, IBM BlueGene, . . .
 - Commodity supercomputers: Beowulf clusters

In the beginning... III



Toward standardization of parallel computing

Until the early/mid 1990s, each supercomputer vendor provides their own parallel computing tools.

- ► Each new parallel computer requires to learn a new or updated environment to get good performance
- Terrible for portability and productivity

The time was ripe for a standardization effort for all types of parallelism.

In the beginning... IV



Toward standardization of parallel models of computation

- Distributed memory models:
 - PVM (1991)
 - MPI standard (1992)
- Shared memory models:
 - POSIX.1c / IEEE Std 1003.1c-1995 a.k.a. PTHREAD library
 - OpenMP standard (1997)

The obvious benefits are portability and productivity, although *performance portability* is not guaranteed (only correctness).

Why should we care about these parallel models? I

Hardware context

- End of Dennard's scaling
- Moore's law now used to add more computing units on a single chip (instead of going to higher frequencies)
- Programming chip multiprocessors (CMP) is not just for scientific/high-performance computing anymore
 - Embedded chips require programming models and execution models to efficiently exploit all of the hardware

Why should we care about these parallel models? II

Software context – embedded systems

A lot of embedded systems are mainstream and general purpose nowadays

- ▶ e.g., Raspberry PI, Beagle, etc.
- They feature CMPs such as ARM multicore chips
- Even on more specialized platforms, MPI, OpenMP, or OpenCL implementations exist:
 - Xilinx proposes a way to synthesize circuits in FPGAs with OpenCL
 - Adapteva's Parallella board: Zynq-7000 = dual core Cortex A9+FPGA SoC + Epiphany co-processor (16 cores with scratchpads).
 - There are OpenMP and MPI implementations for both ARM and Epiphany boards.
 - Bottom line: "general purpose" parallelism is made available to all parallel platforms nowadays

Why should we care about these parallel models? III



Advantages of traditional programming and execution models

- ▶ Because these models are standardized, they are made available in mainstream programming tools
 - OpenMP and MPI both have free/open source implementations available to all
 - Same with PGAS languages
 - Same with GPU-oriented languages
 - Performance goes from "acceptable" to "pretty good"
 - ... but proprietary implementations tend to be faster because they have better/exclusive knowledge of underlying system software and/or hardware
 - ...but not always!

Message-passing execution models

An introduction to MPI

Execution Model

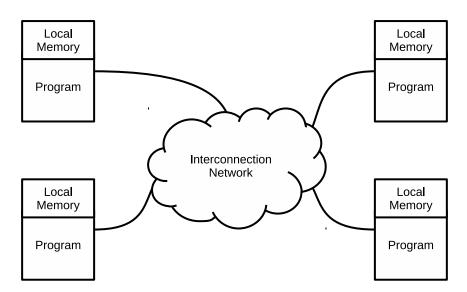
Execution Model

- Relies on the notion of distributed memory
- ▶ All data transfers between MPI processes are explicit
- Processes can also be synchronized with each other
- Achieved using a library API

MPI process \neq UNIX or Windows process.

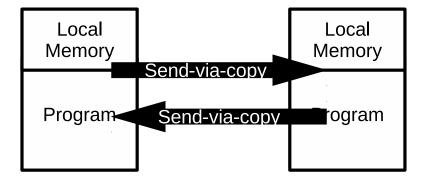
- ightharpoonup A process = a program counter + a (separate) address space
- ➤ An MPI process could be implemented as a thread [Huang, Lawlor, and Kale 2003]

MPI execution model in a nutshell I





MPI execution model in a nutshell II



MPI-1



- ▶ Basic I/O communication functions (100+)
- Blocking send and receive operations
- Nonblocking send and receive operations
- Collective communications
 - Broadcast, scatter, gather, etc.
 - Important for performance
- Datatypes to describe data layouet
- Process topologies (use of communicators, tags)
- ▶ C, C++, Fortran bindings
- ► Error codes and classes

MPI-2 and beyond

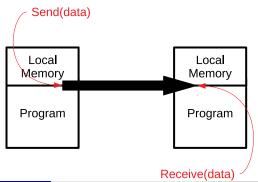


- ▶ MPI-2 (2000):
 - Thread support
 - MPI-I/O, R-DMA
- ▶ MPI-2.1 (2008) and MPI-2.2 (2009):
 - Corrections to standard, small additional features
- ▶ MPI-3 (2012):
 - Lots of new features to standard (briefly discussed at the end)

MPI Basics

Stuff needed by the MPI implementation from application

- ▶ How to compile and run MPI programs
- How to identify processes
- ► How to describe the data



Compiling and running MPI programs

MPI is a library

Need to use function calls, to leverage MPI features.

Compilation

- ▶ Regular compilation: use of cc, e.g., gcc -o test test.c
- ▶ MPI compilation: mpicc -o test test.c

Execution

- ► Regular execution: ./text
- ▶ MPI execution: mpiexec -np 16 ./test

MPI process identification

MPI groups

- ▶ Each MPI process belongs to one or more groups
- ► Each MPI process is given one or more colors
- ► Group+color = *communicator*
- ► All MPI processes belong to MPI_COMM_WORLD when the program starts

Identifying individual processes: ranks

▶ If a process belongs to two different communicators, its rank may be different from the point of view of each communicator.

Most basic MPI program

Hello World

```
#include <mpi.h> // required to use MPI functions
#include <stdio.h>
int main(int argc, char* argv[]) {
    int rank, size;
    must ALWAYS be called to run an MPI program
    MPI_Init(&argc, &argv);
    get process rank/id
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
//
   get total number of processes in communicator
    MPI_Comm_size(MPI_COMM_WOLRD, &size);
    printf("I,am,process,#%d/%d\n", rank, size);
    must ALWAYS be called to run an MPI program
    MPI_Finalize():
    return 0;
}
```

Basic data transfers

MPI_Send



```
Syntax: int MPI_Send (const void *buf, int count, MPI_Datatype datatype, int dest, int tag, MPI_Comm comm)
```

- ▶ buf: the buffer from where to read the data to send
- count: the number of elements to send over the network link
- datatype: the type of data that is being sent, e.g., MPI_CHAR, MPI_INT, MPI_DOUBLE, etc.
- dest: which process is meant to receive the data (identified by its rank)
- ▶ tag: a way to discriminate between various messages sent to the same process rank
- comm: the communicator (or "group of tasks") to target

Basic data transfers

MPI Recv



```
Syntax: int MPI_Recv (const void *buf, int count,
MPI_Datatype datatype, int src, int tag, MPI_Comm comm,
MPI_Status *status)
```

- buf: the buffer from where to write the data to be read
- count: the number of elements to receive over the network link
 - count can be bigger than what was received in practice (the real count can be obtained using MPI_Get_count)
 - If count is smaller than what is being sent, an error occurs
- datatype: the type of data that is being received, e.g., MPI_CHAR, MPI_INT, MPI_DOUBLE, etc.
- dest: from which process the data originates (identified by its rank)
- tag: a way to discriminate between various messages sent to the same receiving process rank
- comm: the communicator (or "group of tasks") to target
- status: contains the source of the message, the tag, how many elements were sent

Basic data transfers I Wildcards & status

Receive wildcards

- MPI_ANY_SOURCE: accepts data from any sender
- ► MPI_ANY_TAG: accepts data with any tag (as long as the receiver is a valid target)

Basic data transfers II

Status object

Wildcards & status

Objects of type MPI_Status have the following accessible fields (assume our object name is status):

- ► MPI_SOURCE: the rank of the process which sent the message (useful when using MPI_ANY_SOURCE)
- ▶ MPI_TAG: the tag used to identify the received message (useful when using MPI_ANY_TAG)
- MPI_ERROR: the error status (assuming the MPI program does not crash when an error is detected—which is the behavior by default).

To get the number of elements received, the user can query status using the MPI_Get_count function.



A simple example to send and receive data

```
#include <mpi.h> // required to use MPI functions
#include <stdio.h>
int main(int argc, char* argv[]) {
  int rank, data[100];
  MPI_Init(&argc, &argv);
  MPI_Comm_rank(MPI_COMM_WORLD, &rank);
  if (rank == 0)
    MPI_Send(data.100.MPI INT.1.0.MPI_COMM_WORLD):
  else
    MPI_Recv(data,100,MPI_INT,0,0,0,MPI_COMM_WORLD,MPI_STATUS_IGNORE);
  MPI_Finalize():
  return 0:
```



MPI is simple

- ► MPI_Init
- ► MPI_Comm_rank
- MPI_Comm_size
- ▶ MPI_Send
- ► MPT Recv
- MPT Finalize

...are enough to write any application using message passing.

However, to be *productive* and ensure reasonable *performance portability*, other functions are required.

MPI pragmatics

Building and running MPI programs

Building MPI programs

- C: mpicc
- ► C++: mpicxx
- ► Fortran: mpif77 (Fortran 77) or mpif90 (Fortran 90)

Running MPI programs

- mpiexec -np 16 ./test
 - ...will run the program test on 16 MPI processes.
- ▶ mpiexec -host $h1, h2, \ldots$ -np 16 ./test
 - ... will run the program test on the various hosts specified on the command line in a round-robin fashion
 - In our example, host h1 will receive MPI processes 0,2,4,6.

Note: mpiexec or mpirun can be used interchangeably (they are aliases).

Non-blocking communications

Limits to MPI_Send and MPI_Recv

MPI_Send and MPI_Recv are blocking communication calls

- ➤ The sending process must wait until the data it is sending has been received
- ➤ The receiving process must block once it has initiated the receiving operation
- Consequence: data sent or received through blocking communications is safe to (re)use
- ► However, this can severely hamper the overall performance of an application

Non-blocking variants: MPI_Isend and MPI_Irecv

- ▶ Routine returns immediately completion has to be tested separately
- ▶ Primarily used to overlap computation and communication

Non-blocking communications I Syntax

API

- ▶ int MPI_Isend(const void *buf, int count, MPI_Datatype
 datatype, int dest, int tag, MPI_Comm comm, MPI_Request
 *request)
- ▶ int MPI_Irecv(const void *buf, int count, MPI_Datatype
 datatype, int dest, int tag, MPI_Comm comm, MPI_Request
 *request)
- int MPI_Wait(MPI_Request *request, MPI_Status *status)

Non-blocking communications II Syntax

Properties

- Non-blocking operations allow overlapping of computation and communication
- Completion can be tested using MPI_Test(MPI_Request *request,
 int flag, MPI_Status *status)
- ► Anywhere one uses MPI_Send or MPI_Recv, one can use MPI_Isend/MPI_Wait or MPI_Irecv/MPI_Wait pairs instead
- ➤ Combinations of blocking and non-blocking sends/receives can be used to synchronize execution instead of barriers

Non-blocking communications III Syntax



Multiple completions

- int MPI_Waitall(int count, MPI_Request
 *array_of_requests, MPI_Status *array_of_statuses)
- int MPI_Waitany(int count, MPI_Request
 *array_of_requests, int *index, MPI_Status *status)
- int MPI_Waitsome(int count, MPI_Request
 *array_of_requests, int *array_of_indices, MPI_Status
 *array_of_status)

There are corresponding versions of MPI_Test for each of those.



A simple example to use non-blocking communications

```
#include <mpi.h>
int main(int argc, char* argv[]) {
  if (rank == 0) {
    for (i=0; i< 100; i++) {
      /* Compute each data element and send it out */
      data[i] = compute(i);
      MPI_ISend(&data[i], 1, MPI_INT, 1, 0, MPI_COMM_WORLD,
                &request[i]);
    }
    MPI_Waitall(100, request, MPI_STATUSES_IGNORE)
  } else {
    for (i = 0: i < 100: i++)
      MPI_Recv(&data[i], 1, MPI_INT, 0, 0, MPI_COMM_WORLD,
               MPI_STATUS_IGNORE):
```

Collective operations

Introduction

- Collective operations are called by all processes belonging to the same communicator
- ▶ MPI_Bcast distributes data from one process (the root) to all others in a communicator
- MPI_Reduce combines data from all processes in the communicator and returns it to one process
- In many (numerical) algorithms, send/receive pairs can be replaced by broadcast/reduce ones
 - Simpler and more efficient

Properties

- Tags are not used; only communicators matter.
- Non-blocking collective operations were added in MPI-3
- ► Three classes of operations: synchronization, data movement, collective computation

Synchronization

int MPI_Barrier(MPI_Comm *comm)

- ▶ Blocks until all processes belonging to communicator comm call it
- No process can get out of the barrier unless all the other processes have reached it

Collective data movements



- ▶ MPI_Bcast
- ▶ MPI_Scatter
- ▶ MPI_Gather
- ▶ MPI_Allgather
- MPI_Alltoall

Collective computations



- ► MPI_Reduce
- ▶ MPI_Scan

Other MPI Collective routines



- Other useful collective operations
 - MPI_Allgatherv
 - MPI_Alltoallv
 - MPI_Gatherv
 - MPI_Scatterv
 - MPI_Reducescatter
- "All" versions deliver results to all participating processes
- "v" versions (stands for vector) allow the chunks to have different sizes
 - Important when the number of processes involved in the computation is no a multiple of the number of data elements
- ► MPI_Allreduce, MPI_Reduce, MPI_Reducescatter, and MPI_Scan take both built-in and user-defined combiner functions.

Built-in collective computation operations



MPI_MAX Maximum
MPI_MIN Minimum

MPI_PROD Product

MPI_SUM Sum

MPI_LAND Logical and MPI_LOR Logical or

MPI_LXOR Logical exclusive or

MPI BAND Bitwise and

MPI_BOR Bitwise or

MPI_BXOR Bitwise exclusive or
MPI_MAXLOC Maximum and location
MPI_MINLOC Minimum and location

Example using collective operations I



```
#include <mpi.h>
#include <math.h>
int main(int argc, char* argv[]) {
  const double g_PI25DT = 3.141592653589793238362643;
  double mypi, pi, h, sum, x, a;
  int     n, myid, numprocs, i, ierr;
  xMPI_Init(&argc, &argv);
  xMPI_Comm_rank(MPI_COMM_WORLD, &myid);
  xMPI_Comm_size(MPLCOMM_WORLD, &numprocs);
  for (;;) {
    if (myid == 0) {
      printf("Enter_the_number_of_intervals:_(0_quits)_");
      fflush(stdout):
      scanf("%f", &n);
      if (n <= 0) break;
    xMPI_Bcast(&n, 1, MPI_INT, 0, MPI_COMM_WORLD);
    if (n < 0) { xMPI_Finalize(); exit(0); }</pre>
```

Example using collective operations II



```
h = 1.0/n; sum = 0.0;
  for (int i = myid+1; i < n; i+=numprocs) {</pre>
    x = h * ((double)i-0.5);
    sum += (4.0 / (1.0 * x*x)):
  }
  mvpi = h*sum;
  xMPI_Reduce(&mypi,&pi,1,MPI_DOUBLE,MPI_SUM,0,MPI_COMM_WORLD);
  if (myid == 0)
    printf("pi_is_\%f._Error_is_\%f\n", pi, fabs(pi-g_PI25DT));
}
xMPI_Finalize();
return 0;
```

Shared-memory execution models

Introduction to OpenMP I

The OpenMP Framework

- Stands for Open MultiProcessing
- ▶ Three languages supported: C, C++, Fortran
- ▶ Supported on multiple platforms: UNIX, Linux, Windows, etc.
 - Very portable
- ▶ Many compilers provide OpenMP capabilities:
 - The GNU Compiler Collection (gcc) OpenMP 3.1
 - Intel C/C++ Compiler (icc) OpenMP 3.1 (and partial support of OpenMP 4.0)
 - Oracle C/C++ OpenMP 3.1
 - IBM XL C/C++ OpenMP 3.0
 - Microsoft Visual C++ OpenMP 2.0
 - etc.

Introduction to OpenMP II

OpenMP's Main Components

- ▶ Compiler directives
- A functions library
- ► Environment variables

The OpenMP Model

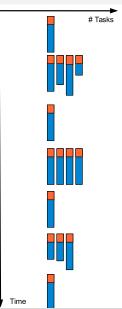


- An OpenMP program is executed using a unique process
- Threads are activated when entering a parallel region
- Each thread executes a task composed of a pool of instructions
- While executing, a variable can be read and written in memory:
 - It can be defined in the stack of a thread: the variable is private
 - It can be stored somewhere in the heap: the variable is shared by all threads

Running OpenMP Programs: Execution Overview

OpenMP: Program Execution

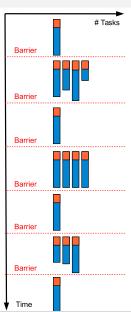
- An OpenMP program is a sequence of serial and parallel regions
- ➤ A sequential region is always executed by the master thread: Thread 0
- A parallel region can be executed by multiple tasks at a time
- ► Tasks can share work contained within the parallel region



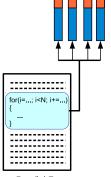
Running OpenMP Programs: Execution Overview

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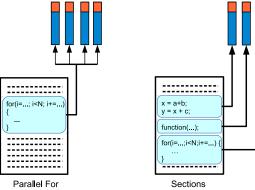


▶ Parallel loops

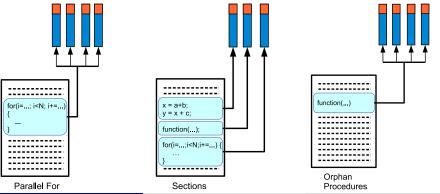


Parallel For

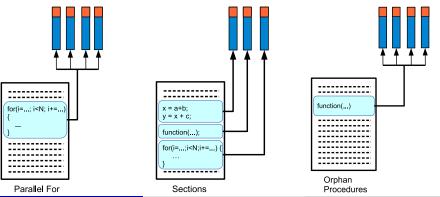
- ▶ Parallel loops
- Sections



- ▶ Parallel loops
- Sections
- Procedures through orphaning



- ► Parallel loops
- Sections
- Procedures through orphaning
- Tasks



OpenMP Structure I

Compilation Directives and Clauses

They define how to:

- Share work
- Synchronize
- Share data

They are processed as comments unless the right compiler option is specified on the command line.

Fonctions and Subroutines

They are part of a library loaded at link time

OpenMP Structure II

Environment Variables

Once set, their values are taken into account at execution time

OpenMP vs. MPI I

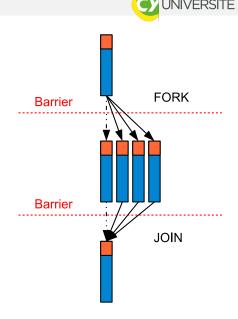


These two programming models are complementary:

- ▶ Both OpenMP and MPI can interface using C, C++, and Fortran
- ▶ MPI is a multi-process environment whose communication mode is explicit (the user is in charge of handling communications)
- OpenMP is a multi-tasking environment whose communication between tasks is implicit (the compiler is in charge of handling communications)
- In general, MPI is used on multiprocessor machines using distributed memory
- ▶ OpenMP is used on multiprocessor machines using shared memory
- On a cluster of independent shared memory machines, combining two levels of parallelism can significantly speed up a parallel program's execution.

OpenMP: Principles

- The developer is in charge of introducing OpenMP directives
- When executing, the OpenMP runtime system builds a parallel region relying on the "fork-join" model
- When entering a parallel region, the master task spawns ("forks") children tasks which disappear or go to sleep when the parallel region ends
- Only the master task remains active after a parallel region is done



Principal Directives I

Creating a Parallel Region: the parallel Directive

```
#pragma omp parallel
{
     /* Parallel region code */
}
```

Principal Directives II

Data Sharing Clauses

- shared(...): Comma-separated list of all variables that are to be shared by all OpenMP tasks
- private(...): Comma-separated list of all variables that are to be visible only by their task.
 - Variables that are declared private are "duplicated:" their content is unspecified
 when entering the parallel region, and when leaving the region, the privatized
 variable retains the content it had before entering the parallel region
- firstprivate(...): Comma-separated list of variables whose content must be copied (and not just allocated) when entering the parallel region.
 - The value when leaving the parallel remains the one from before entering it.
- default(none|shared|private): Default policy w.r.t. sharing variables. If not specified, defaults to "shared"

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A First Example: Hello World



```
szuckerm@evans201g:examples$ gcc -std=c99 -Wall -Wextra -pedantic \
-03 -o omp_hello omp_hello.c
```

```
#include <stdio.h>
                                                     examples$ ./hello
#include <stdlib.h>
                                                     [0] Hello, World!
#include <omp.h>
#ifndef OPENMP
                                                     [3] Hello, World!
                                                     [1] Hello, World!
#define omp_get_thread_num() 0
                                                     [2] Hello, World!
#endif
int main(void)
{
    #pragma omp parallel
        int tid = omp_get_thread_num();
        printf("[%d]\tHello, World!\n", tid);
    return EXIT_SUCCESS;
```

Figure: omp_hello.c

Example: Privatizing Variables



```
#include <stdio.h>
#include <omp.h>
int main() {
    float a = 1900.0;
    #pragma omp parallel default(none) private(a)[3] a = 716.00
    {
        a = a + 716.;
        printf("[%d]\tau=u%.2f\n",omp_get_thread_num(), a);
    }
    printf("[%d]\tau=u%.2f\n",omp_get_thread_num(), a);
    return 0;
}
```

Sharing Data Between Threads



```
examples:$ gcc -std=c99 -Wall -Wextra -pedantic -03 \
-o omp_hello2 omp_hello2.c
```

```
#include <stdio.h>
                                                      examples$ ./hello2
#include <stdlib.h>
                                                      [0] Hello, World!
#include <omp.h>
#ifndef OPENMP
                                                      [3] Hello, World!
                                                      [1] Hello, World!
#define omp_get_thread_num() 0
                                                      [2] Hello, World!
#endif
int main(void)
{
    int ids[] = \{0, 1, 2, 3, 4, 5, 6, 7\};
    #pragma omp parallel default(none) shared(ids)
        printf("[%d]\tHello, \( \text{World!\n", ids[omp_get_thread_num()])};
    return EXIT_SUCCESS;
```

Capturing Privatized Variables' Initial Values



szuckerm@evans201g:examples\$ gcc -std=c99 -Wall -Wextra -pedantic -O3\
-o omp_firstprivate omp_firstprivate.c

```
#include <stdio.h>
                                                     examples$ ./omp_firstprivate
#include <omp.h>
                                                     a = 19716.000000
int main() {
                                                     a = 19716.000000
     float a = 1900.0:
                                                     a = 19716.000000
                                                     a = 19716.000000
     #pragma omp parallel \
                                                     a = 19000.000000
       default(none) firstprivate(a)
          a = a + 716.:
          printf("a_{\sqcup} = {\sqcup} \% f \n",a);
     printf("a_{\parallel}=_{\parallel}\%f \setminus n",a);
     return 0:
```

Figure: omp_firstprivate.c

Scope of OpenMP Parallel Regions



When calling functions from a parallel region, local and automatic variables are implicitly private to each task (they belong to their respective task's stack). Example:

```
#include <stdio.h>
#include <omp.h>
void sub(void);
int main(void) {
    #pragma omp parallel default(shared)
         sub();
    return 0:
void sub(void) {
    int a = 19716;
           += omp_get_thread_num();
    printf("a_{\sqcup} = {\sqcup} %d \n", a);
```



szuckerm@evans201g:examples\$ gcc -std=c99 -Wall -Wextra -pedantic -O3\
-o omp_for parallel_for.c

```
#include <stdio.h>
                                             examples$ ./omp_for
#include <omp.h>
                                              [1] Hellow, World!
                                              [0] Hellow, World!
int.
                                              [3] Hellow, World!
main(void)
                                              [2] Hellow, World!
{
    #pragma omp parallel
         int n_threads = omp_get_num_threads();
         #pragma omp for
         for (int i = 0; i < n_threads; ++i) {</pre>
             printf("[%d]\tHellow, World!\n", i);
```

Figure: parallel_for.c

Parallel Loops: A Few Things to Remember

- The iterator of a omp for loop must use additions/substractions to get to the next iteration (no i *= 10 in the postcondition)
- The iterator of the outermost loop (which directly succeeds to the omp for directive) is always private, but not the ones in other nested loops!
- There is an implicit barrier at the end of the loop. You can remove it by adding the clause nowait on the same line: #pragma omp for nowait
- 4 How the iterations are distributed among threads can be defined using the schedule clause.

Specifying the Schedule Mode

The syntax to define a scheduling policy is schedule(ScheduleType, chunksize). The final line should like this:

```
#pragma omp parallel default(none) \
                     shared(...) private(...) firstprivate(...)
    #pragma omp for schedule(...) lastprivate(...)
    for (int i = InitVal; ConditionOn(i); i += Stride)
    \{ /* loop body */ \}
// or, all in one directive:
#pragma omp parallel for default(none) shared(...) private(...) \
                         firstprivate(...) lastprivate(...)
    for (int i = InitVal; ConditionOn(i); i += Stride) {
      /* loop body */
```

Specifying the Schedule Mode

The number of iterations in a loop is computed as follows:

$$NumIterations = \left\lfloor \frac{|FinalVal - InitVal|}{Stride} \right\rfloor + |FinalVal - InitVal| \mod Stride$$

The number of *iteration chunks* is thus computed like this:

$$\textit{NumChunks} = \left\lfloor \frac{\textit{NumIterations}}{\textit{ChunkSize}} \right\rfloor + \textit{NumIterations} \bmod \textit{ChunkSize}$$

Parallel Loops III Specifying the Schedule Mode



Static Scheduling

schedule(static,chunksize) distributes the iteration chunks across threads in a round-robin
fashion

- Guarantee: if two loops with the same "header" (precondition, condition, postcondition, and chunksize for the parallel for directive) succeed to each other, the threads will be assigned the same iteration chunks
- By default, chunksize is equal to OMP_NUM_THREADS
- Very useful when iterations take roughly the same time to perform (e.g., dense linear algebra routines)

Dynamic Scheduling

schedule(dynamic,chunksize) divides the iteration space according to chunksize, and creates an "abstract" queue of iteration chunks. If a thread is done processing its chunk, it dequeues the next one from the queue. By default, chunksize is 1.

Very useful if the time to process individual iterations varies.

Parallel Loops IV Specifying the Schedule Mode



Guided Scheduling

guided, chunksize Same behavior as dynamic, but the chunksize is divided by two each time a threads dequeues a new chunk. The minimum size is one, and so is the default.

Very useful if the time to process individual iterations varies, and the amount of work has a

Very useful if the time to process individual iterations varies, and the amount of work has a "trail"

Specifying the Schedule Mode I



```
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
const double MAX = 100000.;
double sum(const int n) {
    const int id = omp_get_thread_num();
    double f = 0.0;
    const int bound = id == 0 ? n*1001 : n:
    for (int i = 0; i < bound; ++i)
      f += i;
    return f;
```

Specifying the Schedule Mode II



```
int main(void) {
  printf("MAX_{\square} = _{\square} \%.2f \n", MAX);
  double acc = 0.0;
  int* sum until = malloc(MAX*sizeof(int));
  if (!sum_until) perror("malloc"), exit( EXIT_FAILURE );
  for (int i = 0; i < (int)MAX; ++i) sum_until[i] = rand () % 100;
  #pragma omp parallel default(none) \
               shared(sum_until) firstprivate(acc)
    /* Use the OMP_SCHEDULE environment variable on the command
      * line to specify the type of scheduling you want, e.q.:
      * export OMP_SCHEDULE="static" or OMP_SCHEDULE="dynamic, 10"
      * or OMP_SCHEDULE="quided,100"; ./omp_schedule
   #pragma omp for schedule(runtime)
    for (int i = 0; i < bound; i+=1) {</pre>
        acc += sum( sum_until[i] );
    printf ("[%d]\tMy_sum_=;\%.2f\n", omp_get_thread_num(), acc);
  free(sum_until);
  return 0:
                        Figure: omp_for_schedule.c
```

Specifying the Schedule Mode: Outputs I

```
UNIVERSITÉ
```

```
szuckerm@evans201g:examples$ gcc -std=c99 -Wall -Wextra -pedantic \
-03 -o omp_schedule omp_for_schedule.c
szuckerm@evans201g:examples$_export_OMP_NUM_THREADS=4_OMP_PROC_BIND=true
```

Specifying the Schedule Mode: Outputs I

```
UNIVERSITÉ
```

```
szuckerm@evans201g:examples$ gcc -std=c99 -Wall -Wextra -pedantic \
-03 -o omp_schedule omp_for_schedule.c
szuckerm@evans201g:examples$ export DMP_NUM_THREADS=4 DMP_PRDC_BIND=true
```

```
szuckerm@evans201g:examples$ export OMP_SCHEDULE="static,1"
szuckerm@evans201g:examples$ time ./omp_schedule
MAX = 100000.00

[0] My sum = 41487115603934.00

[1] My sum = 4026669.00

[3] My sum = 40319644.00

[2] My sum = 4046898.00

real Om11.312s
user Om11.356s
sys OM0.004s
```

Specifying the Schedule Mode: Outputs II



```
szuckerm@evans201g:examples$ export OMP_SCHEDULE="dynamic,1000"
szuckerm@evans201g:examples$ time ./omp_schedule
MAX = 100000.00
[0] My sum = 1661647855868.00
[1] My sum = 55011312.00
[2] My sum = 46974801.00
[3] My sum = 58218664.00

real Om0.546s
user Om0.576s
sys.Om0.004s
```

szuckerm@evans201g:examples\$ export OMP_SCHEDULE="dynamic,1000"

Parallel Loops

Specifying the Schedule Mode: Outputs II

szuckerm@evans201g:examples\$ time ./omp schedule



```
MAX = 100000.00
[0] My sum = 1661647855868.00
[1] My sum = 55011312.00
[2] My sum = 46974801.00
[3] My sum = 58218664.00
real
        0m0 546s
       0m0.576s
user
sys 0m0.004s
szuckerm@evans201g:examples$ export OMP SCHEDULE="dynamic.1"
szuckerm@evans201g:examples$ time ./omp_schedule
MAX = 100000.00
[1] Mv sum = 57886783.00
[0] My sum = 76809786053.00
[2] My sum = 47423265.00
[3] My sum = 56452544.00
```

0m0.023s

0m0 059s

real

user svs 0m0.004s

Specifying the Schedule Mode: Outputs III



Specifying the Schedule Mode: Outputs III

szuckerm@evans201g:examples\$ time ./omp schedule

szuckerm@evans201g:examples\$ export OMP_SCHEDULE="guided,1000"



```
MAX = 100000.00
[0] My sum = 30922668944167.00
[3] My sum = 44855495.00
[2] My sum = 45989686.00
[1] My sum = 40596797.00
real
        0m8 437s
       0m8.452s
user
sys 0m0.008s
szuckerm@evans201g:examples$ export OMP SCHEDULE="guided.1"
szuckerm@evans201g:examples$ time ./omp_schedule
MAX = 100000.00
[0] My sum = 17508269385607.00
[1] My sum = 49603788.00
[2] My sum = 40584346.00
[3] My sum = 54438904.00
```

0m5.401s

0m5 438s

real

user 0m5.4

The lastprivate Clause



```
int main(void) {
    double acc = 0.0; const int bound = MAX;
    printf("[%d]\tMAX_=_\%.2f\n",omp_get_thread_num(),MAX);
    int* sum_until = smalloc(MAX*sizeof(int));
    for (int i = 0; i < bound; ++i)</pre>
        sum_until[i] = rand () % 100;
    #pragma omp parallel for default(none) shared(sum_until) \
                schedule(runtime) firstprivate(acc) lastprivate(acc)
    for (int i = 0; i < bound; i+=1)
        acc += sum( sum_until[i] );
    printf("Value_of_the_last_thread_to_write_to_acc_=_%.2f\n",acc);
    free(sum until):
    return EXIT SUCCESS:
                       Figure: omp_for_lastprivate.c
```

Incrementing a Global Counter I



```
Racy OpenMP Version
```

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
unsigned long g_COUNTER = 0;
int.
main(void)
  int n_threads = 1;
  #pragma omp parallel default(none) \
              shared(n_threads, stdout, g_COUNTER)
  {
    #pragma omp master
      n_threads = omp_get_num_threads();
      printf("n_threads_=_\%d\t",n_threads); fflush(stdout);
    ++g_COUNTER;
  printf("g_COUNTER_=_%lu\n",g_COUNTER);
```

Incrementing a Global Counter II Racy OpenMP Version



```
return EXIT_FAILURE;
}
```

Incrementing a Global Counter

Using a Critical Section



```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
unsigned long g_COUNTER = 0;
int main(void) {
  int n threads = 1:
  #pragma omp parallel default(none) \
              shared(n_threads,stdout,g_COUNTER)
  {
    #pragma omp master
      n_threads = omp_get_num_threads();
      printf("n_threads"="\%d\t",n_threads); fflush(stdout);
    #pragma omp critical
    { ++g_COUNTER; }
  printf("g_COUNTER_=_%lu\n",g_COUNTER);
  return EXIT FAILURE:
```

Incrementing a Global Counter

Using an Atomic Section



```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
unsigned long g_COUNTER = 0;
int main(void) {
  int n threads = 1:
  #pragma omp parallel default(none) \
              shared(n_threads,stdout,g_COUNTER)
  {
    #pragma omp master
      n_threads = omp_get_num_threads();
      printf("n_threads_=\%d\t",n_threads); fflush(stdout);
    #pragma omp atomic
    ++g_COUNTER;
  printf("g_COUNTER_=_%lu\n",g_COUNTER);
  return EXIT FAILURE:
```

Synchronization in OpenMP I

critical Directive

```
#pragma omp critical [(name)]
```

Guarantees that only one thread can access the sequence of instructions contained in the (named) critical section. If no name is specified, an "anonymous" name is automatically generated.

atomic Directive

```
#pragma omp atomic
```

Guarantees the atomicity of the *single* arithmetic instruction that follows. On architectures that support atomic instructions, the compiler can generate a low-level instruction to ensure the atomicity of the operation. Otherwise, atomic is equivalent to critical.

Synchronization in OpenMP II

barrier Directive

#pragma omp barrier

All threads from a given parallel region must wait at the barrier. All parallel regions have an implicit barrier. All omp for loops do too. So do single regions.

single Directive

Guarantees that a single thread will execute the sequence of instructions located in the single region, and the region will be executed only once. There is an implicit barrier at the end of the region.

Synchronization in OpenMP III



master Directive

Guarantees that only the master thread (with ID=0) will execute the sequence of instructions located in the single region, and the region will be executed only once. There is NO implicit barrier at the end of the region.

nowait Clause

nowait can be used on omp for, single, and critical directives to remove the implicit barrier they feature.

Tasking in OpenMP



OpenMP 3.x brings a new way to express parallelism: tasks.

- ► Tasks must be created from within a single region
- ► A task is spawned by using the directive #pragma omp task
- ► Tasks synchronize with their siblings (i.e., tasks spawned by the same parent task) using #pragma omp taskwait

Case Study: Fibonacci Sequence



We'll use the Fibonacci numbers example to illustrate the use of tasks:

	Average Time (cycles)
Sequential - Recursive	196051726.08

Table: Fibonacci(37), 50 repetitions, on Intel i7-2640M CPU @ 2.80GHz

Computing Fibonacci Numbers: Headers I



```
#ifndef UTILS_H_GUARD
#define UTILS H GUARD
#include <stdio.h>
#include <stdlib.h>
#include <errno.h>
#include <stdint.h>
#include "rdtsc.h"
static inline void fatal(const char* msg) {
    perror(msg), exit(errno);
static inline void sfree(void* p) {
    if (p) { *(char*)p = 0;} free(p);
static inline void* scalloc(size t nmemb. size t size) {
 void* p = calloc(nmemb, size);
  if (!p) { fatal("calloc"); }
  return p:
static inline void* smalloc(size_t size) {
```

Computing Fibonacci Numbers: Headers II



Computing Fibonacci Numbers: Headers III



```
#ifndef COMMON_H_GUARD
#define COMMON H GUARD
#include "utils.h" // for smalloc(), sfree(), fatal(), scalloc(), ....
#define FIB THRESHOLD 20
typedef uint64_t u64; typedef uint32_t u32; typedef uint16_t u16;
typedef uint8_t u8; typedef int64_t s64; typedef int32_t s32;
typedef int16 t s16: typedef int8 t s8:
u64 xfib(u64): u64 trfib(u64.u64.u64):
u64 trFib(u64); u64 sfib(u64);
u64 memoFib(u64); u64
                        memofib(u64,u64*);
void* mt_memofib(void*); u64  mt_memoFib(u64);
void* mtfib(void*): u64 mtFib(u64):
u64 oFib(u64); u64 ofib(u64);
u64
    o memoFib(u64): u64 o memofib(u64.u64*):
```

Computing Fibonacci Numbers: Headers IV



```
#endif /* COMMON H GUARD */
#ifndef MT H GUARD
#define MT_H_GUARD
#include <pthread.h>
typedef struct memofib_s { u64 *up, *vals, n; } memofib_t;
static inline pthread_t* spawn(void* (*func)(void*), void* data) {
    pthread_t* thread = smalloc(sizeof(pthread_t)); int error = 0;
    do {
      errno = error = pthread create(thread.NULL.func.data):
    } while (error == EAGAIN);
    if (error) fatal("pthread_create");
    return thread;
static inline void sync(pthread_t* thread) {
    int error = 0; void* retval = NULL;
    if ( (errno = ( error = pthread_join(*thread, &retval) ) ) )
        fatal("pthread_join");
    sfree(thread);
```

Computing Fibonacci Numbers: Headers V



```
| }
| #endif // MT_H_GUARD
```

Computing Fibonacci Numbers: Code I Naïve Pthread and OpenMP



```
#include "common.h"
#include "mt.h"
void* mtfib(void* frame) {
    fib t*f = (fib t*) frame:
    u64 n = f->n, *up = f->up;
    if (n < FIB THRESHOLD)</pre>
        *up = sfib(n), pthread_exit(NULL);
    u64 n1 = 0, n2 = 0:
    fib_t frame1 = \{ .up = &n1, .n = f->n-1 \},
          frame2 = { .up = &n2, .n = f \rightarrow n-2 };
    pthread_t *thd1 = spawn(mtfib,&frame1),
               *thd2 = spawn(mtfib,&frame2);
    sync(thd1); sync(thd2);
    *up = n1+n2;
    return NULL;
u64 mtFib(u64 n) {
    u64 result = 0; fib_t f = { .up = &result, .n = n };
    (void) mtfib(&f);
    return result:
```

Computing Fibonacci Numbers: Code II Naïve Pthread and OpenMP



```
#include "common.h"
#include <omp.h>
u64 ofib(u64 n) { u64 n1, n2;
    if (n < FIB_THRESHOLD) return sfib(n);</pre>
    pragma omp task shared(n1)
    n1 = ofib(n-1);
    pragma omp task shared(n2)
    n2 = ofib(n-2);
    pragma omp taskwait
    return n1 + n2;
u64 \text{ oFib}(u64 \text{ n}) \{ u64 \text{ result} = 0;
    pragma omp parallel
#
         pragma omp single nowait
         { result = ofib(n); }
    } // parallel
    return result;
```

Computing Fibonacci Numbers: Code III Naïve Pthread and OpenMP



	Average Time (cycles)
Sequential - Recursive	196051726.08
Parallel - PThread	2837871164.24
Parallel - OpenMP	17707012.14

Table: Fibonacci(37), 50 repetitions, on Intel i7-2640M CPU @ 2.80GHz

Computing Fibonacci Numbers: Code I Memoization using Serial, Pthread and OpenMP



```
#include "common.h"
#include "mt.h"
void* mt_memofib(void* frame) { memofib_t* f = (memofib_t*) frame;
  u64 n = f \rightarrow n * vals = f \rightarrow vals, *up = f \rightarrow up;
  if (n < FIB_THRESHOLD) *up = vals[n] = sfib(n), pthread_exit(NULL)</pre>
  if (vals[n] == 0) { u64 n1 = 0, n2 = 0;
    memofib_t frame1 = \{.up=&n1,.n=f->n-1,.vals=vals\},
               frame2 = {.up=&n2, .n=f->n-2, .vals=vals};
    pthread_t *thd1 = spawn(mt_memofib,&frame1),
               *thd2 = spawn(mt memofib.&frame2):
    sync(thd1); sync(thd2);
    vals[n] = n1 + n2;}
  *up = vals[n], pthread_exit(NULL);
u64 \text{ mt memoFib}(u64 \text{ n}) \{ u64 \text{ result} = 0:
    u64* fibvals = scalloc(n+1, sizeof(u64));
    fibvals[1]=1; memofib_t f={.up=&result,.n=n,.vals=fibvals};
    (void) mt memofib (&f):
    return result;
```

Computing Fibonacci Numbers: Code II



```
Memoization using Serial, Pthread and OpenMP
#include "common.h"
#include <omp.h>
u64 o_memofib(u64 n, u64* vals) {
  if (n < FIB THRESHOLD) return sfib(n):
  if (vals[n] == 0) { u64 n1 = 0, n2 = 1;
    pragma omp task shared(n1, vals)
    n1 = o_memofib(n-1, vals);
    pragma omp task shared(n2, vals)
    n2 = o_memofib(n-2, vals);
    pragma omp taskwait
    vals[n] = n1 + n2;
  return vals[n];
u64 o memoFib(u64 n) {
  u64 result=0, *fibvals=calloc(n+1, sizeof(u64));
# pragma omp parallel
    pragma omp single nowait
    { fibvals[1] = 1; result = o_memofib(n,fibvals); }
  return result; }
```

Computing Fibonacci Numbers: Code III Memoization using Serial, Pthread and OpenMP



```
#include "common.h"
u64 memofib(u64 n, u64* vals) {
    if (n < 2)
        return n:
    if (vals[n] == 0)
        vals[n] = memofib(n-1, vals) + memofib(n-2, vals);
    return vals[n]:
u64 memoFib(u64 n) {
    u64* fibvals = calloc(n+1, sizeof(u64));
    fibvals[0] = 0; fibvals[1] = 1;
    u64 result = memofib(n,fibvals);
    sfree(fibvals):
    return result:
```

Computing Fibonacci Numbers: Code IV Memoization using Serial, Pthread and OpenMP



	Average Time (cycles)
Sequential - Recursive	196051726.08
Parallel - PThread	2837871164.24
Parallel - OpenMP	17707012.14
Parallel - PThread - Memoization	2031161888.56
Parallel - OpenMP - Memoization	85899.58
Sequential - Memoization	789.70

Table: Fibonacci(37), 50 repetitions, on Intel i7-2640M CPU @ 2.80GHz

Computing Fibonacci Numbers: Code I When Serial is MUCH Faster Than Parallel



```
#include "common.h"
u64 trfib(u64 n, u64 acc1, u64 acc2) {
    return n < 2 ?
        acc2 :
        trfib( n-1, acc2, acc1+acc2);
}
u64 trFib(u64 n) { return trfib(n, 0, 1); }</pre>
```

```
#include "common.h"
u64   sfib(u64 n) {
    u64   n1 = 0, n2 = 1, r = 1;
    for (u64 i = 2; i < n; ++i) {
        n1 = n2;
        n2 = r;
        r = n1 + n2;
    }
    return r;
}</pre>
```

Computing Fibonacci Numbers: Code II When Serial is MUCH Faster Than Parallel



	Average Time (cycles)
Sequential - Recursive	196051726.08
Parallel - PThread	2837871164.24
Parallel - OpenMP	17707012.14
Parallel - PThread - Memoization	2031161888.56
Parallel - OpenMP - Memoization	85899.58
Sequential - Memoization	789.70
Sequential - Tail Recursive	110.78
Sequential - Iterative	115.02

Table: Fibonacci(37), 50 repetitions, on Intel i7-2640M CPU @ 2.80GHz

Learning More About Multi-Threading and OpenMP

Books (from most theoretical to most practical)

- ► Herlihy and Shavit 2008
- Rünger and Rauber 2013
- ► Kumar 2002
- ► Chapman, Jost, and Pas 2007

Internet Resources

- ▶ "The OpenMP® API specification for parallel programming" at openmp.org
 - Provides all the specifications for OpenMP, in particular OpenMP 3.1 and 4.0
 - Lots of tutorials (see http://openmp.org/wp/resources/#Tutorials)
- ▶ The Wikipedia article at http://en.wikipedia.org/wiki/OpenMP

Food for Thoughts

- ▶ Sutter 2005 (available at http://www.gotw.ca/publications/concurrency-ddj.htm)
- ▶ Lee 2006 (available at http://www.eecs.berkeley.edu/Pubs/TechRpts/2006/EECS-2006-1.pdf)
- Boehm 2005 (available at http://www.hpl.hp.com/techreports/2004/HPL-2004-209.pdf)

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